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Duality between random trap and barrier models

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Abstract

We discuss the physical consequences of a duality between two models with quenched disorder, in which particles propagate in one dimension among random traps or across random barriers. We derive an exact relation between their diffusion fronts at fixed disorder and deduce from this that their disorderaveraged diffusion fronts are exactly equal. We use effective dynamics schemes to isolate the different physical processes by which particles propagate in the models and discuss how the duality arises from a correspondence between the rates for these different processes.

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1. Introduction

How do classical particles in heterogeneous environments propagate? This question arises in many contexts, from glass-forming liquids and colloids [1, 2], to biomolecules moving in the crowded environment of the cell [3], to electrical properties of disordered materials [4]. Diffusion is the most familiar mode of propagation, but if the heterogeneity involves a sufficiently broad distribution of time scales then slower motion (subdiffusion) is possible: for some reviews of this well-studied field, see [5-8].

Important experimental evidence of subdiffusive motion in disordered environments was obtained a long time ago, through the electrical conductivity of hollandite (a quasi one-dimensional ionic conductor). Here, the charge carriers can be modelled by classical particles on one-dimensional chains: their anomalous low frequency conductance was attributed to subdiffusive motion and modelled by a simple one-dimensional disordered model [4]. More recently, subdiffusive propagation has been important when considering dynamically heterogeneous relaxation in glass formers. There is considerable evidence (for example, [1, 2, 9, 10]) that while time scales grow very fast with decreasing temperature, the length scales associated with dynamical heterogeneity increase rather slowly. In the picture of the glass transition based on dynamical facilitation [11-13], this implies a subdiffusive propagation

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of mobility through the system³. Several possible mechanisms have been proposed for such an effect, such as directional kinetic constraints [12] or a strong dependence of the dynamics on the local free volume [16]. Thus, understanding how subdiffusive motion arises in simple models remains an important challenge.

In this paper, we discuss the physical processes that lead to subdiffusive propagation in two very simple one-dimensional models. They are directly relevant for materials such as hollandite [4], and for the models of glassy behaviour discussed in [16], but they have also been related to the motion of defects in disordered magnets, to disordered elastic chains and to networks of resistors and capacitors (see [5, 7] for reviews). In the first model, diffusive motion is frustrated by the presence of sites where the particle gets trapped for a long time; in the second, there are barriers between sites across which motion is very slow. These models are related by a duality relation between their master operators. This relation has been noted before [5, 7, 17], but with limited discussion of its physical content. Here, we revisit the duality between the two models, focusing on their diffusion fronts, and derive exact relations between these which do not appear to have been noticed previously. We connect the evolution of the diffusion fronts with the events in which the particle escapes from deep traps or surmounts large barriers. We elucidate the physical processes underlying the duality and use it to motivate an effective dynamics for the model, following le Doussal, Monthus and Fisher [18].

We define our models in section 2 and discuss the duality relation in section 3. We cast the duality relation for fixed disorder as a local relation between the propagators of our models and show that it leads to equal disorder-averaged propagators in the two systems. In section 4, we describe the physical processes by which the models evolve and use them to define effective dynamics schemes. The extent to which this dynamics captures the real-time evolution of the diffusion front is also discussed. We summarize our conclusions in section 5.

2. Models

We first define the random trap model [7]. Consider a single particle hopping on a chain of sites. A particle on site *n* may hop either to the left or right, and hops in both directions happen with the same (site-dependent) rate, W_n . The master equation for the distribution of particle positions, $p_n^{\rm T}$, is then

$$(d/dt)p_n^{\rm T}(t) = W_{n+1}p_{n+1}^{\rm T}(t) + W_{n-1}p_{n-1}^{\rm T}(t) - 2W_n p_n^{\rm T}(t).$$
⁽¹⁾

The superscript 'T' distinguishes quantities for the trap model from those for the barrier model. In the latter [5, 7], the rates W_n are associated not with sites, but with links between them. That is, hops from site n to n + 1 happen with rate W_n , as do hops from site n + 1 to n. In this case, the master equation is

$$(d/dt)p_n^{B}(t) = W_n \left[p_{n+1}^{B}(t) - p_n^{B}(t) \right] + W_{n-1} \left[p_{n-1}^{B}(t) - p_n^{B}(t) \right].$$
(2)

In [7], it was noted that if the same set of rates W_n are used in both models, then the current in the barrier model $j_n^{\rm B} = W_n (p_n^{\rm B} - p_{n+1}^{\rm B})$ obeys the same differential equation as the rescaled probability density $W_n p_n^{\rm T}$ in the trap model. This duality between trap and barrier models was noted a long time ago by Dyson [17]: we refer to it as 'trap-barrier duality'. As explained below, it follows that the eigenspectra of the two master operators are

³ Subdiffusive propagation is characterized by a dynamical exponent z, which describes the relative scaling of space and time at a critical point. For example, the fragile models considered in [14] exhibit subdiffusive behaviour, with z > 2. In the Fredrickson–Andersen model considered in [15], the scaling at the critical point is diffusive, with z = 2. Away from criticality, the correlation length ξ and correlation time τ satisfy $D\tau \sim \xi^2$, where D is the diffusion constant. However, D itself has a non-trivial temperature dependence, so the temperature scaling cannot in general be written as $\tau \sim \xi^2$.

equal for these two models: this property is relevant for the impedances of linear chains of resistors and capacitors, and for the elasticity of random one-dimensional chains. However, in understanding how particles propagate in disordered media, the most natural quantity is the propagator, or diffusion front, which we discuss in some detail below.

It was further argued in [7] that trap-barrier duality can be understood by identifying the regions between large barriers in one model with the deep traps in the other. While very appealing intuitively, this argument is possibly somewhat misleading, in two opposite ways. On the one hand, it suggests that the duality holds only after suitable coarse-graining to large lengths and times; we will see, however, that for the diffusion fronts it is valid on *all* length and time scales. On the other hand, viewing a barrier model as consisting of effective traps would suggest that, at least on large enough scales, the models will behave effectively identically. This also is not quite correct. For example, the barrier model has a stationary distribution in which the particle occupies each site with equal probability, while the trap model exhibits ageing behaviour if it is initialized in a uniform state [19]. Quantitatively, consider a particle that starts from the origin at time zero and measure its mean-square displacement between times t' and t > t'. Averaging over the random rates W_n according to a translationally invariant distribution, we have (see section 3) that

$$R^{2}(t,t') = \langle [x(t) - x(t')]^{2} \rangle$$
(3)

depends only on the time difference t - t' in the barrier model (the angle brackets represent an average over the stochastic dynamics and the overbar represents the average over the rates W_n). On the other hand, in the trap model, $R^2(t, t')$ generically depends on both time arguments, and for the disorder distributions we will consider it never reaches a stationary regime in the thermodynamic limit.

Bearing this and other differences in mind, we now use the relationship between (1) and (2) to investigate the extent to which the barrier model can be modelled by a set of effective traps. We establish relationships between the propagators (diffusion fronts) of the two models and use this analysis to develop a physical picture of propagation in these systems. We also show that the duality implies not just that the long-time behaviour of these models are the same, but that their disorder-averaged propagators are identical at all times. We contrast the extent to which the models are similar with differences between them, including their ageing behaviour and the properties of the typical particle trajectories.

3. Duality

It is convenient to define the master operator for the barrier model, \hat{W}^{B} , in terms of its matrix elements W_{nm}^{B} , by writing (2) as $(d/dt)p_{n}^{B}(t) = -\sum_{m} W_{nm}^{B}p_{m}^{B}(t)$. We specify periodic boundaries on a chain of length *L*, so this operator has *L* eigenvectors q_{n}^{B} . The eigenvector with zero eigenvalue gives the steady state $q_{n}^{B,eq} = 1/L$. The dynamics of the model obeys detailed balance with respect to this trivial distribution, as is clear from the symmetry $W_{nm}^{B} = W_{mn}^{B}$. For the trap model we call the master operator \hat{W}^{T} ; it too obeys detailed balance but with respect to the non-uniform steady state $q_{n}^{T,eq} \propto W_{n}^{-1}$.

The expression of trap-barrier duality in terms of propagators can be derived from the simple fact that if $p_n^B(t)$ is a solution of the barrier model master equation (2) then $p_n^B(t) - p_{n+1}^B(t)$ is a solution of the trap model equation (1). Applying this to a barrier model eigensolution $p_n^B(t) = q_n^B \exp(-\lambda t)$, it follows that $q_n^T = q_n^B - q_{n+1}^B$ is an eigenvector for the trap model master operator with the same eigenvalue λ . This is a one-to-one relation between the eigenvectors with nonzero eigenvalues of the two master operators, and so their spectra are identical as claimed in section 2. (Inverting the differencing relation to get from q^T back to $q^{\rm B}$ in principle gives an undetermined constant, but this is fixed by the requirement that nonzero eigenvectors obey $\sum_n q_n^{\rm B} = 0$.) The exception is the steady state, where differencing the barrier model steady state $q^{\rm B,eq} = 1/L$ gives a vanishing result rather than the trap model steady state.

The propagator or diffusion front of the barrier model, $G_{n \leftarrow i}^{B}(t)$, is defined as the solution of (2) with initial condition $p_{n}^{B}(0) = \delta_{n,i}$. This can also be obtained from matrix elements of the time evolution operator: $G_{n \leftarrow i}^{B}(t) = [\exp(-\hat{W}^{B}t)]_{ni}$. The symmetry of the barrier master operator \hat{W}^{B} then implies that also the propagator is symmetric under interchange of arrival and departure sites

$$G_{n \leftarrow i}^{\mathrm{B}}(t) = G_{i \leftarrow n}^{\mathrm{B}}(t) \tag{4}$$

as required for a system obeying detailed balance with respect to a uniform distribution.

We now turn to the trap-barrier duality relation for the propagators. Since $p_n^{\rm B}(t) = G_{n \leftarrow i}^{\rm B}(t)$ is the solution to (2) with initial condition $p_n^{\rm B}(0) = \delta_{n,i}$, it follows that $p_n^{\rm T}(t) = G_{n \leftarrow i}^{\rm B}(t) - G_{n+1 \leftarrow i}^{\rm B}(t)$ is a solution of (1), with initial condition $p_n^{\rm T}(0) = \delta_{n,i} - \delta_{n+1,i} = \delta_{n,i} - \delta_{n,i-1}$. Defining the propagator for the trap model $G_{n \leftarrow i}^{\rm T}(t)$ as the solution to (1) with initial condition $p_n^{\rm T}(0) = \delta_{n,i}$, it follows (by linearity of the master equation) that

$$G_{n \leftarrow i}^{\rm B}(t) - G_{n+1 \leftarrow i}^{\rm B}(t) = G_{n \leftarrow i}^{\rm T}(t) - G_{n \leftarrow i-1}^{\rm T}(t).$$
(5)

This identity, which holds for all realizations of the disorder $\{W_n\}$, is our desired exact statement of the trap-barrier duality relation, in terms of the propagators of the two models. It can be used to express the trap model propagator in terms of the barrier model one and vice versa. For example, since the diffusion front vanishes at large distances, we have

$$G_{n \leftarrow i}^{\mathrm{B}}(t) = \sum_{j=n}^{L/2} \left[G_{j \leftarrow i}^{\mathrm{B}}(t) - G_{j+1 \leftarrow i}^{\mathrm{B}}(t) \right] = \sum_{j=n}^{L/2} \left[G_{j \leftarrow i}^{\mathrm{T}}(t) - G_{j \leftarrow i-1}^{\mathrm{T}}(t) \right].$$
(6)

(We require that the chain length *L* is large enough that $G_{j \leftarrow i}^{B}$ does indeed vanish at large *j*. That is, *L* should be taken to infinity before taking any limit of large time.) A corresponding relation can be used to express G^{T} in terms of G^{B} . We show typical propagators in figure 1 and give a geometrical interpretation of (5): the difference of the barrier model propagator taken between neighbouring *arrival* sites equals the negative difference of the trap model propagator between neighbouring *departure* sites.

In making the plots in figure 1 we considered the most common case where W_n are independently and identically distributed (i.i.d.) with a distribution

$$P(W) \propto W^{(1/\mu)-1}, \qquad 0 < W < 1.$$
 (7)

With this choice, the long time behaviour of a particle is diffusive for $\mu < 1$ and subdiffusive for $\mu > 1$. More precisely, if a particle begins on a randomly chosen site, its displacement at large times scales as [7, 20]

$$\langle x^2(t) \rangle \sim t^{2/z}, \qquad z = \max(2, 1 + \mu)$$
 (8)

with logarithmic corrections for $\mu = 1$.

It is sometimes useful to interpret the rates W_n as arising from activation energies E_n associated with crossing a barrier or leaving a trap. We then write $W_n = \exp(-E_n/T)$, where *T* is the temperature and we have set Boltzmann's constant equal to unity. In this representation, assuming the distribution of the activation energies is $P(E) = \exp(-E)$ with E > 0, we can identify μ with 1/T.

We now consider averaging the propagators G^{B} and G^{T} over realizations of the disorder. For any distribution of the disorder which is translationally invariant (which includes all



Figure 1. Top: sample propagators, $G_{n \leftarrow i}^{T}$ and $G_{n \leftarrow i}^{B}$, as a function of final site *n*, for trap and barrier models at $\mu = 3$. The set of disordered rates is the same in each case, and we take i = 0 and $t = 2^{14}$. Small rates lead to sites with peaks in the trap model propagator and to large changes between adjacent sites in the barrier model. Middle: propagator maps for the same systems—the propagators at fixed time are plotted as functions of both initial and final positions. The dashed lines indicate n = i and the dotted lines with arrows indicate the slices for which we plot data in the other panels of this figure. In the trap model, the probability is concentrated on final sites with small escape rates. In the barrier model, it is delocalized across 'effective traps', separated by barriers with small escape rates. The duality relation (5) states that the gradient of the trap model propagator with respect to *i* is equal to the negative gradient of the barrier model propagator with respect to *n*. The relevant gradient in the barrier model is localized on the upper and lower edges of the effective traps, and these are the final sites on which the probability is localized in the trap model. Bottom: we plot the trap model propagator as a function of initial site *i*, for a fixed final site n = 4. This illustrates its gradient with respect to *i*.

choices in which the W_n are i.i.d.), the disorder-averaged propagators depend only on the difference m = n - i. Using a bar to denote the disorder average as before, we thus have from the duality relation (5)

$$\overline{G}_{m}^{\mathrm{B}}(t) - \overline{G}_{m+1}^{\mathrm{B}}(t) = \overline{G}_{m}^{\mathrm{T}}(t) - \overline{G}_{m+1}^{\mathrm{T}}(t).$$
(9)

Since both propagators must vanish as $|m| \rightarrow \infty$, it follows that

$$\overline{G}_{m}^{\mathrm{B}}(t) = \overline{G}_{m}^{\mathrm{T}}(t).$$
(10)

This exact coincidence of the disorder-averaged diffusion fronts is a surprising result. For a given realization of the disorder, the propagators for the two models are very different, as shown in figure 1. For other quantities the difference is even more striking. Consider for example the quantity $R^2(t, t')$ defined in (3). Since all propagators decay to zero at large distances, we can replace the disorder average by an average over initial position i, so that $R^{2}(t, t') = (1/L) \sum_{k,n} (x_{n} - x_{k})^{2} G_{n \leftarrow k}(t - t') \sum_{i} G_{k \leftarrow i}(t')$, where x_{n} is the position of site *n*. But now the symmetry (4) of the barrier model propagator together with conservation of probability implies $\sum_{i} G_{k \leftarrow i}(t') = \sum_{i} G_{i \leftarrow k}(t') = 1$. Thus $R^{2}(t, t')$ depends on t and t' only through the propagator $G_{n \leftarrow m}(t - t')$ and therefore only through the time difference t - t'. The argument evidently generalizes to the entire (disorder-averaged) distribution of x(t) - x(t'). This time translation invariance arises because a particle moving among barriers is equally likely to be on any site, whether or not it is bordered by a high barrier. In the trap model, on the other hand, the particle spends (for $\mu > 1$) most of its time in deep traps whose escape rate decreases with the age t' as $W \sim t'^{(1/z)-1}$ [7]. To arrive at the asymptotic scaling of $R^2(t, t')$ in the trap model, we take t > t', and note that moves to left and right are always equally likely, so that $\langle [x(t) - x(t')]x(t') \rangle = 0$ (for any realization of the disorder, as long as the system size L is taken to infinity before any limit of large time⁴). Thus, $R^2(t, t') = \langle x^2(t) \rangle - \langle x^2(t') \rangle$, which for large t and t' scales as $t^{2/z} - t^{2/z}$. Clearly, time translational invariance is obtained only in the diffusive case (z = 2 or $\mu < 1$).

The difference between the two models in the subdiffusive regime $\mu > 1$ can also be seen at the level of typical trajectories. For example, let *N* be the mean number of hops made by a particle up to time *t*. Time translation invariance in the barrier model implies that $N \sim t$. To get the scaling (8), the displacement must then grow with the number of hops as $|x| \sim N^{1/z}$, i.e. more slowly than for simple diffusion. On the other hand, in the trap model, the typical number of hops associated with trajectories of displacement |x| scales as in simple diffusion: $N \sim |x|^2$, because escapes from any trap occur with equal probability to the left and the right. This then implies a number of hops growing only sublinearly in time, $N \sim t^{2/z}$ [7].

To summarize thus far, the trap and barrier models have on average equal diffusion fronts, but many other physical properties differ. Motivated by this surprising observation, we now discuss the duality relation at fixed disorder in more detail, in order to understand how the equality of the disorder-averaged diffusion fronts arises.

4. Effective dynamics

In figure 1, we showed the propagators for trap and barrier models, for a single realization of the disorder (with $\mu = 3$) and at a given time. To understand how the propagators evolve in time we exploit an 'effective dynamics picture' in the spirit of [18]. A very similar scheme was applied to the trap model in [21, 22]. This effective dynamics is based on an assumption of well-separated time scales, which is valid in the limit of large μ taken at fixed energies E_n . We first present the scheme for the barrier model.

4.1. Barrier model

To define the effective dynamics in this model, we separate those barriers which are relevant on a time scale t from those which are irrelevant. Large barriers (those with small transmission

⁴ To see this, use (1) to obtain $(d/dt) \sum_{n=N}^{M} (x_n - x_k) G_{n \leftarrow k}^{T}(t) = (x_M - x_N) [W_N G_{N \leftarrow k}^{T}(t) - W_M G_{M \leftarrow k}^{T}(t)]$. Taking site *M* far to the right of site *k* and site *N* far to its left, this time derivative vanishes. Therefore, using the initial condition for G^T , we have $\sum_n (x_n - x_k) G_{n \leftarrow k}^{T}(t) = 0$. Hence, $\langle [x(t) - x(t')]x(t') \rangle = \sum_{nk} (x_n - x_k) x_k G_{n \leftarrow k}^{T}(t - t') G_{n \leftarrow i}^{T}(t') = 0$.

$$\begin{array}{c|c} \textbf{Barrier.} i.....k\\ G^{\text{B}}_{n \leftarrow m}(t_0) & & & \\ \textbf{Site} i & m & j & k \\ \end{array} \\ \begin{array}{c} \textbf{Site} i & m & j \\ \textbf{Site} i & m & j \\ \end{array} \\ \begin{array}{c} \textbf{Site} i & m & j \\ \textbf{Site} i & m & j \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m & j \\ \textbf{Site} i & m & j \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m & j \\ \textbf{Site} i & m & j \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m & j \\ \textbf{Site} i & m & j \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array} \\ \begin{array}{c} \textbf{G}^{\text{T}}_{n \leftarrow m}(t_1) \\ \textbf{Site} i & m \\ \textbf{Site} i & m \\ \end{array}$$
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Figure 2. Left: sketch illustrating a single step of the effective dynamics for the barrier model. Barriers *i*, *j* and *k* are all relevant at time t_0 , so $G_{n \leftarrow m}^B(t_0)$ is localized between barriers *i* and *j*. At the later time t_1 , barrier *j* has become irrelevant ($K_j t_1 > 1$). Right: a sketch of the corresponding behaviour for the trap model. The propagator is localized on sites *i* and *j* at the initial time t_0 and on sites *i* and *k* at the later time t_1 . The value of the propagator on these sites is in inverse proportion to their distance from the initial site *m*.

rates W) tend to be relevant, because they limit the motion of the particle. Once we have identified a set of relevant barriers, we assume that particles move rapidly between them, but never cross them. Thus, for an initial site m, we have

$$G_{n \leftarrow m}^{\mathrm{B}}(t) = \begin{cases} (j-i)^{-1}, & i < n \leq j \\ 0, & \text{otherwise} \end{cases}$$
(11)

where i is the index of the nearest relevant barrier to the left of site m and j the index of the nearest relevant barrier to its right (see figure 2). These two barriers define the 'effective trap' within which the particle is localized. In the propagator map representation of figure 1, the effective dynamics models the propagator as a series of non-overlapping blocks. As the set of relevant barriers evolves in time, the map evolves by instantaneous events in which two adjacent blocks coalesce into a single larger one.

To obtain the time scale on which barriers cease to be relevant, suppose that the two barriers delimiting the effective trap have well-separated transmission rates, $W_j \gg W_i$. On time scales much smaller than W_i^{-1} , the diffusion front evolves in time only by transmission through barrier *j*. The diffusion front increases within a neighbouring effective trap, which is formed by barrier *j*, and the nearest relevant barrier to its right (let the index of this barrier be *k*, as in figure 2). We now further assume that the motion between barriers *j* and *k* is fast compared to transmission through them. In that case, we can approximate the propagator by

$$G_{n \leftarrow m}^{\mathrm{B}}(t) = \begin{cases} \rho_0(t), & i < n \leq j \\ \rho_1(t), & j < n \leq k \end{cases}$$
(12)

where ρ_0 and ρ_1 are probability densities within the two effective traps (to the left and right of barrier *j*, see figure 2). The probabilities in these traps are $\rho_0 l_0$ and $\rho_1 l_1$, where $l_0 = j - i$ and $l_1 = k - j$ are the sizes of the effective traps. These probabilities evolve as $\partial_t [l_0 \rho_0(t)] = -\partial_t [l_1 \rho_1(t)] = W_j [\rho_1(t) - \rho_0(t)]$. Hence,

$$\partial_t [\rho_0(t) - \rho_1(t)] = -K_j [\rho_0(t) - \rho_1(t)], \tag{13}$$

and we identify

$$K_j = W_j \left(\frac{1}{l_0} + \frac{1}{l_1}\right) \tag{14}$$

as the rate for equilibration between these two effective traps.

Still working within our assumptions of well-separated time scales, we can use this procedure to define the time evolution of the set of relevant barriers. At small times, all barriers are relevant. For a given set of relevant barriers, we characterize barrier j by its value of K_j , where the lengths l_0 and l_1 are the distances to the nearest relevant barriers to the left



Figure 3. Left: propagator map for the barrier model at $\mu = 10$ and $t = 2^{29}$. This was calculated by histogramming the corresponding trap model propagator and using (5). Right: propagator map for the effective dynamics, using the same realization of the disorder and the same final time. The agreement is quite good, although the real propagator has some fine structure not captured by the effective dynamics.

and right of barrier *j*. (When a relevant barrier is removed, a new effective trap is formed, and the values of K_j on the adjacent barriers change according to the width of the new trap.) Thus, the effective dynamics evolves in time by successive removal of the barrier with the largest value of K_j . To obtain the set of relevant barriers at time *t*, this procedure is iterated until all relevant barriers have $K_j t < 1$. The propagator is then constructed using (11), as described above.

This approach is similar to that of [18], differing only in that the sizes of the effective traps enter the transition rates. This is necessary for this model, since these factors affect the scaling of the diffusion front (see section 4.3). We also note that the rate K_j depends symmetrically on the width of the effective traps to the left and the right of the barrier. This ensures that the effective dynamics for the diffusion front preserves its symmetry (4).

We now revisit our assumptions regarding well-separated time scales. These assumptions were (i) that the two barriers delimiting each effective trap have well-separated rates, allowing us to treat transmission over them independently, (ii) the rates associated with successive stages of the effective dynamics are well separated and so the time taken for a given barrier to become irrelevant is well approximated by K_j^{-1} and (iii) equilibration within each of two neighbouring effective traps is faster than transitions between them [so that (12) can be applied]. Writing $W_n = \exp(-E_n/T)$ as before, with $T = 1/\mu$, we recall that the distribution of energies is $P(E_n) = \exp(-E_n)$. For the first assumption, the time scales for crossing adjacent barriers are well-separated if the difference between their two energies is much greater than T. In the limit of low temperature (or large μ) the probability of finding two adjacent barriers with rates within T of each other vanishes, so this assumption holds. For the second assumption, the same argument implies that the rate for any stage of the dynamics is well separated from the (larger) rate of the previous stage. Finally, for the third assumption, the rate for equilibration within an effective trap is of the order of the rate of a previous stage of the effective dynamics, which is well separated from the rate of the current stage as per the second assumption.

In figure 3, we compare the propagator for a given realization of the disorder with the prediction of the effective dynamics, at $\mu = 10$. The agreement is quite good, justifying our assumptions of well-separated time scales at this value of μ . As μ is decreased from this large value towards unity, these assumptions break down. The result is that the propagator cannot be well approximated by non-overlapping blocks in the density map representation (recall the structure of the propagator at $\mu = 3$, shown in figure 1). We discuss the agreement between effective and real dynamics in more detail in section 4.3, at the level of the disorder-averaged

diffusion front. First, though, we construct an effective dynamics for the trap model, related to the effective dynamics of the barrier model by the duality relation (5).

4.2. Trap model

Since we have the duality relation (5), the effective dynamics that we have described for the propagator of the barrier model has a corresponding effective dynamics in the trap model. We begin by describing this effective dynamics in terms of physical processes in the trap model and then we show that it is indeed the dual of that of the barrier model.

We assume that for a given initial site *m*, the propagator is concentrated on two 'relevant' traps on sites *i* and *j*, with i < j. As before, if time scales are well separated then we can consider these two sites separately. If $W_i \ll W_j$, the relevant physical processes are those in which the particle escapes from trap *j* and falls into another relevant trap: either the one on site *i* or one located on a site k > j (see figure 2). The particle hops from site *j* to j + 1 with rate W_j . However, the probability of it reaching site *k* before being reabsorbed on site *j* is 1/(k - j). (Particles always hop left and right with equal probability, so this combinatorial factor is the same as for simple diffusion.) Thus, the rates for motion from site *j* to sites *i* and *k* are $W_j/(j - i)$ and $W_j/(k - j)$, respectively. We therefore identify the total rate for moving from site *j* to either neighbouring trap as K_j , as defined in (14). This is the time scale on which the trap on site *j* becomes irrelevant. Hence, the effective dynamics for the set of relevant rates in the trap model is the same as the effective dynamics for those in the barrier model.

It remains to find the value of the propagator on these relevant sites. Starting from a single trap on site *m*, with i < m < j, the rates for arriving on sites *i* and *j* are in inverse proportion to their relative distances from *m*. Therefore, if at time t_0 trap *m* has become irrelevant then $G_{i \leftarrow m}^{T}(t_0) = (j - m)/(j - i)$ and $G_{j \leftarrow m}^{T}(t_0) = (m - i)/(j - i)$. In the next step of the process, site *j* becomes irrelevant, by time t_1 say, and the probability on that site is redistributed onto sites *k* and *i*, with probabilities inversely proportional to their distances from site *j*. Thus, we can relate the propagator at t_1 to that at t_0 by $G_{i \leftarrow m}^{T}(t_1) = G_{i \leftarrow m}^{T}(t_0) + \frac{k-j}{k-i}G_{j \leftarrow m}(t_0) = \frac{k-m}{k-i}$ and $G_{k \leftarrow m}^{T}(t_1) = \frac{j-i}{k-i}G_{j \leftarrow m}^{T}(t_0) = \frac{m-i}{k-i}$. The relative probabilities of the two relevant sites at time t_1 are thus in inverse proportion to their distances from the initial site *m*, just as they were at time t_0 . Hence, this property is maintained as successive barriers become irrelevant.

These arguments motivate us to define our effective dynamics for the diffusion front as

$$G_{n \leftarrow m}^{\mathrm{T}} = \frac{j - m}{j - i} \delta_{n,i} + \frac{m - i}{j - i} \delta_{n,j}$$

$$\tag{15}$$

where *i* and *j* are the nearest relevant traps to the left and right of the initial site *m*, and the set of relevant traps is determined by successively removing the trap with the smallest value of K_j . A similar result was derived in [21], although relevant traps were identified by their values of W_j in that work. These choices seem to be equivalent in the limit of large μ in which the effective dynamics schemes are valid. Returning to our analysis, it is then trivial to check that (15) and (11) are consistent with the duality relation (5) and that they are therefore dual to each other. The comparison between effective and real dynamics for the *barrier* model was shown in figure 3. Since both real and effective dynamics obey the duality relation, the agreement is similarly good for the trap model.

Thus, we have identified the physical processes leading to motion in the trap model and used these processes to motivate an effective dynamics for the diffusion front. This effective dynamics is related by the trap-barrier duality of (5) to that defined in the previous section for the barrier model. We trace this symmetry to the equality between the rates K_j for the (different) physical processes that occur in the two models.



Figure 4. Top: plots of $\langle x^2(t) \rangle$, comparing real dynamics (symbols) and effective dynamics (solid lines). The dashed lines show the power-law scaling of (8), with unit prefactors (we plot $\langle x^2 \rangle = t^{2/(1+\mu)}$). The effective dynamics captures the time dependence of the mean-squared displacement quantitatively, even at the relatively small value $\mu = 3$. Bottom: we show the disorder-averaged diffusion front $\overline{G}_n(t)$ for real dynamics (points) and effective dynamics (lines) at $\mu = 10$ (left) and $\mu = 3$ (right). The times are those of the final points in the top panel, $t = 2^{49}$ and $t = 2^{22}$: the data of that panel indicate that these times are long enough to be representative of the asymptotic large-time scaling. The effective dynamics agrees well with the real dynamics for $\mu = 10$, but for the smaller μ the agreement deteriorates because the assumption of well-separated time scales breaks down.

4.3. Disorder-averaged diffusion fronts

Turning to disorder-averaged properties of the effective dynamics, the scaling (8) for $\mu > 1$ arises directly from the form of the rate K_j given in (14). To demonstrate this, we use the language of the barrier model. Let the typical distance between relevant barriers at time *t* be $\langle \ell(t) \rangle$. (Unlike distributions of times, all moments of the distribution of lengths are finite, so scaling arguments based on typical widths are valid.) Since relevant barriers have Kt < 1, the rates *W* associated with these barriers typically satisfy $Wt < \langle \ell(t) \rangle$. For consistency, the typical distance between these barriers must scale as $\langle \ell(t) \rangle$, so we have

$$\langle \ell(t) \rangle^{-1} \sim \int_0^{\langle \ell(t) \rangle/t} P(W) \,\mathrm{d}W \tag{16}$$

where P(W) was given in (7). This leads to $t \sim \ell(t)^{1+\mu}$. All length scales in the effective dynamics scale with $\ell(t)$, so this dynamics lead to $z = 1 + \mu$, giving the correct scaling of the diffusion front for all $\mu > 1$ (recall (8)).

Following the reasoning in [18], scaling arguments can also be used to express the disorder-averaged diffusion front in terms of the fraction of effective traps of length ℓ at time *t*. In the scenarios studied in [18, 21], where the widths of all effective traps and the rates of the relevant barriers are all independent, this allows one to make significant progress. By contrast, in our effective dynamics the relevance of barriers is determined by K_i , and this introduces

correlations between the rates and the widths of the effective traps. We have therefore not been able to determine the required distribution of trap lengths ℓ analytically, and instead return to numerical simulations.

In figure 4, we compare the predictions of the effective dynamics with simulations of the trap and barrier models. At long times, we find good quantitative agreement at $\mu = 10$. At $\mu = 3$, the effective dynamics still captures the width of the distribution, although the absence of well-separated time scales leads to deviations in the tail. The diffusion front for the trap model was considered in [23], where it was predicted to decay as $\overline{G}_n(t) \sim |n|^{(-\mu+1)/2\mu} \exp[-b|n|^{(\mu+1)/\mu}]$, for large *n* and μ close to unity (in our notation, the parameter μ of [23] is denoted by $1/\mu$). While our results are consistent with this prediction, our statistics are not good enough to accurately determine the asymptotic scaling of the tails of the diffusion front. Overall, we would argue that our results indicate that the proposed effective dynamics does indeed capture the physical processes responsible for propagation in the trap and barrier models.

5. Conclusions

We have discussed several implications of the duality between one-dimensional trap and barrier models, including (5), which is an exact local relation between their diffusion fronts valid for fixed disorder, and (10), which states that their disorder-averaged propagators are equal. In addition, we have presented a unified effective dynamics for diffusion fronts in the large μ limit of the trap and barrier models. This dynamics captures the scaling of the diffusion front and gives good quantitative estimates of its width. Our arguments indicate that it gives the exact shape of the diffusion front in the limit of extreme subdiffusion ($\mu \rightarrow \infty$), with agreement becoming less good as the system approaches the diffusive regime ($\mu < 1$).

The effective dynamics exploits the fact that in both models the time scale on which traps and barriers become irrelevant depends on both their rates W and on the spacings between them. In the barrier model, the dependence on spacings arises from the fact that if the relevant barriers are well separated, the particle spends only a small fraction of its time adjacent to them. In the trap model, it originates from the fact that a particle leaving a given trap is likely to be reabsorbed there before it can reach a neighbouring deep trap. Despite the different physical mechanisms, these two processes affect the diffusion front in closely related ways and mathematically result in the master operators for these processes having equal eigenspectra.

Thus, for the purposes of the diffusion front, it is indeed appropriate to consider the barrier model as representing an environment of effective traps in which a particle diffuses. However, as we discussed, the trajectories by which the system evolves in each case are different. The effective dynamics illustrates the nature of these trajectories: in the barrier model, the particle diffuses rapidly within its effective trap, leading to a number of hops growing as $N \sim t$. In the trap model, the particle is localized in deep traps, making excursions from its current trap which mostly lead to reabsorption within that trap. The mean hopping rate decreases with time as the system ages [19], leading to $N \sim t^{2/z}$. It would be illuminating to investigate whether the duality relation (5) at fixed disorder can be cast as a relation between the particle trajectories in the barrier and trap models, to see whether these different scalings emerge naturally.

Given the different physical processes underlying the dynamics of the models, we argue that the relationships between the diffusion fronts are, to a certain extent, coincidental. They do not represent a physical equivalence of the models themselves and they do not generalize in a simple way to correlation functions other than the diffusion front. However, it seems to us that the equality of the disorder-averaged propagators and the associated algebraic structure might be exploited in further analytic work on these models.

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